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PROBLEM STATEMENT TITLE: Vigileye Intrusion
Alert System

PROTOTYPE NAME: Intruguard

THEME: Home Security

TEAM NAME: Apex Innovators

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Hardware components used:

Component (General Name)	Model / Specification
Microcontroller	Glyph H2
Ultrasonic Sensor	HC-SR04
IR Sensor	Generic IR Sensor Module
CAP1203 Touch Sensor	CAP1203
DHT22 (Temperature & Humidity)	DHT22
SW-420 Vibration Sensor	SW-420
Connecting wires	Jumper wires / standard hookup wires
Breadboard	Standard solderless breadboard
Power supply	3.3 V regulated supply
Resistors	10 kΩ, 4.7 kΩ, 220 Ω (optional for LEDs)

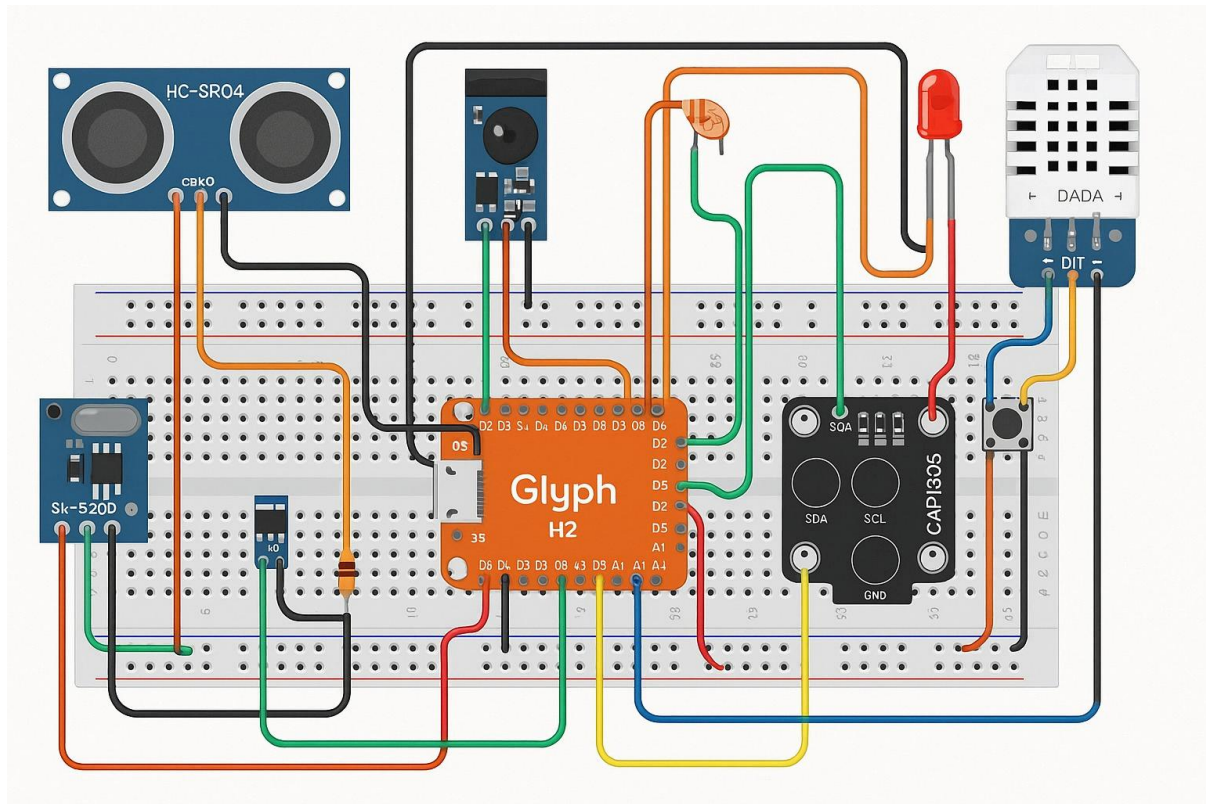
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Pin configuration and circuit connections:

Component	Pin on Component	Pin on Glyph H2	Additional Notes / Resistor
Ultrasonic Sensor (TRIG)	TRIG	GPIO5	—
Ultrasonic Sensor (ECHO)	ECHO	GPIO4	10 k Ω + 20 k Ω voltage divider to reduce 5 V $\rightarrow$ 3.3 V
IR Sensor	OUT	GPIO12	—
CAP1203 Touch Sensor	SDA	GPIO2	I ² C SDA
CAP1203 Touch Sensor	SCL	GPIO3	I ² C SCL
DHT22 Temperature & Humidity	DATA	GPIO14	4.7 k Ω pull-up to 3.3 V
SW-420 Vibration Sensor	OUT	GPIO13	Optional 10 k Ω pull-down
SW-420 Vibration Sensor	VCC	3.3 V	—
SW-420 Vibration Sensor	GND	GND	—
Power Supply	3.3 V / GND	3.3 V / GND	—

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Circuit design/schematic diagrams:



Code:

```
#include <DHT.h>

#include <Wire.h>

#include "SparkFun_CAP1203.h"

// ===== DHT22 setup =====

#define DHTPIN 2    // GPIO2

#define DHTTYPE DHT22

DHT dht(DHTPIN, DHTTYPE);

// ===== IR sensor =====

#define IR_PIN 12    // GPIO12 (active-low)
```

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```
// ===== Ultrasonic sensor =====
```

```
#define TRIG_PIN 5 // GPIO5
```

```
#define ECHO_PIN 4 // GPIO4
```

```
// ===== CAP1203 touch sensor =====
```

```
#define SDA_PIN 8
```

```
#define SCL_PIN 9
```

```
CAP1203 capSensor;
```

```
// ===== Tilt Sensor =====
```

```
#define TILT_PIN 13 // GPIO13 connected to SW-520D
```

```
// ===== LEDs =====
```

```
#define RED_LED 23 // GPIO23 → 220Ω → Red LED → GND
```

```
#define GREEN_LED 24 // GPIO24 → 220Ω → Green LED → GND
```

```
void setup() {
```

```
  Serial.begin(115200);
```

```
  // IR
```

```
  pinMode(IR_PIN, INPUT);
```

```
  // Ultrasonic
```

```
  pinMode(TRIG_PIN, OUTPUT);
```

```
  pinMode(ECHO_PIN, INPUT);
```

```
  // DHT22
```

```
  dht.begin();
```

```
  dht.readHumidity(); // dummy read
```

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```
// CAP1203
```

```
Wire.begin(SDA_PIN, SCL_PIN);
```

```
if (!capSensor.begin()) {
```

```
    Serial.println("CAP1203 not connected. Check wiring.");
```

```
    while (1);
```

```
}
```

```
// Tilt Sensor
```

```
pinMode(TILT_PIN, INPUT_PULLUP);
```

```
// LEDs
```

```
pinMode(RED_LED, OUTPUT);
```

```
pinMode(GREEN_LED, OUTPUT);
```

```
Serial.println("Glyph H2 - Sensors + LED (Ultrasonic Ignored) Test Started");
```

```
Serial.println("-----");
```

```
}
```

```
void loop() {
```

```
    bool alert = false; // assume safe
```

```
    // --- IR Sensor ---
```

```
    int irState = digitalRead(IR_PIN);
```

```
    if (irState == LOW) { // active-low
```

```
        Serial.println("IR: Object detected ");
```

```
        alert = true;
```

```
    } else {
```

```
        Serial.println("IR: No object ");
```

```
}
```

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```
// --- Ultrasonic Sensor (ignored for LED logic) ---

digitalWrite(TRIG_PIN, LOW);

delayMicroseconds(2);

digitalWrite(TRIG_PIN, HIGH);

delayMicroseconds(10);

digitalWrite(TRIG_PIN, LOW);


long duration = pulseIn(ECHO_PIN, HIGH, 30000); // 30ms timeout
float distance = duration * 0.034 / 2;          // in cm
if (duration == 0) {
    Serial.println("Ultrasonic: Out of range");
} else {
    Serial.print("Ultrasonic: "); Serial.print(distance); Serial.println(" cm");
}


// --- DHT22 Sensor ---

float h = dht.readHumidity();
float t = dht.readTemperature();
if (isnan(h) || isnan(t)) {
    Serial.println("DHT22: Failed to read ");
    alert = true;
} else {
    Serial.print("DHT22: Temp: "); Serial.print(t);
    Serial.print("°C, Humidity: "); Serial.print(h); Serial.println("%");
}


// --- CAP1203 Sensor ---

bool touchState = capSensor.isTouched();
if (touchState) {
```

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```
Serial.println("CAP1203: Touch detected ");

alert = true;

} else {

    Serial.println("CAP1203: No touch");

}

// --- Tilt Sensor ---

int tiltState = digitalRead(TILT_PIN);

if (tiltState == HIGH) { // HIGH = Tilt detected

    Serial.println("Tilt: Detected ");

    alert = true;

} else {

    Serial.println("Tilt: Not tilted");

}


// --- LED Control ---

if (alert) {

    digitalWrite(RED_LED, HIGH);

    digitalWrite(GREEN_LED, LOW);

} else {

    digitalWrite(RED_LED, LOW);

    digitalWrite(GREEN_LED, HIGH);

}

Serial.println("-----");

delay(500); // delay for stability

}
```


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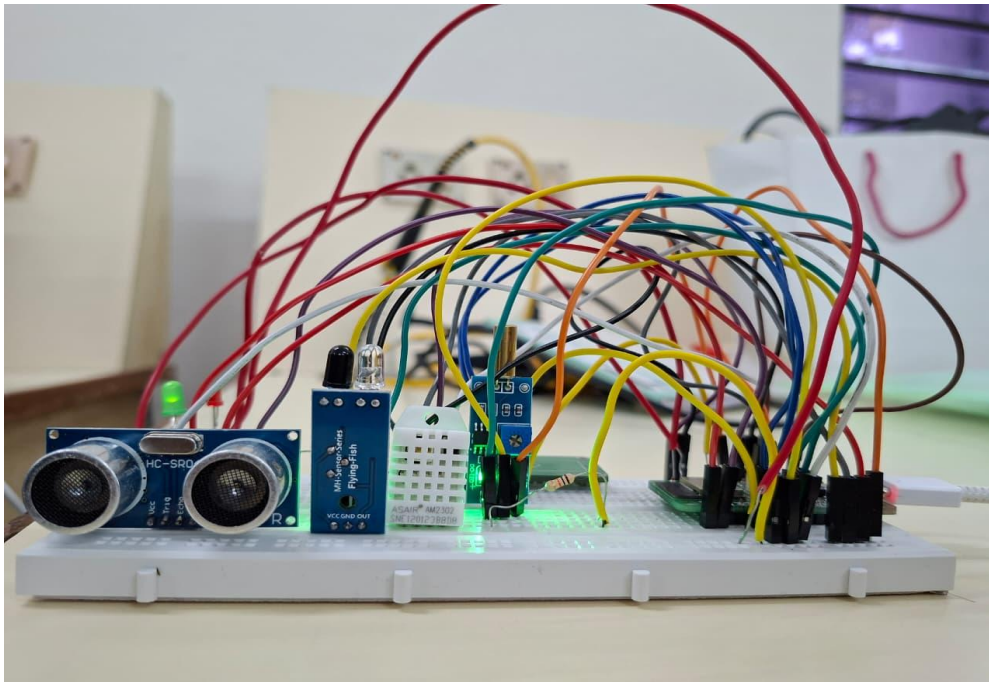
Software / Tools Used:

Arduino IDE – for programming the Glyph H2 microcontroller

Visual Studio Code – for writing dashboard code

HTML, CSS, JavaScript – for creating the web dashboard interface

Pictures of the setup/prototype:



Working explanation and output:

Overview:

The Vigil Eye Intrusion Alert System is a multi-sensor security solution designed to detect unauthorized entry, tampering, and environmental changes in real-time. It integrates an ultrasonic sensor and IR sensor for accurate entry detection, a vibration sensor (SW-420) for tamper alerts, and a CAP12r03 touch sensor for touch detection. The system also monitors temperature and humidity using a DHT22 sensor.

Data can be viewed through a web dashboard created using HTML, CSS, and JavaScript, providing real-time alerts and environmental monitoring. This compact, low-cost system is suitable for homes, offices, and public spaces, combining safety, hygiene, and convenience in one platform.

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Entry Detection:

- The Ultrasonic Sensor (HC-SR04) measures the distance of approaching objects.
- The IR Sensor confirms the presence of a person.
- When IR detects an object (regardless of ultrasonic reading), the system triggers the Red LED alert.
- If no detection occurs, the Green LED remains ON, indicating a safe/idle state.

Vibration / Tamper Detection:

- The SW-420 Vibration Sensor detects any vibration or tampering at the door or device.
- When vibration is detected, the system immediately triggers the Red LED alert.
- If no vibration is detected, the system continues to show Green LED, indicating normal status.

Touch Reset:

- The **CAP1203 Touch Sensor** allows a touch-based input.
- When touched, it triggers the **Red LED alert**, simulating an alert action.
- When not touched, it reports **No touch detected**.
- Touch can be used to reset alert counters or acknowledgment in some designs.

Environmental Monitoring:

- The DHT22 Sensor continuously reads temperature and humidity.
- If readings are successful, they are printed to the Serial Monitor.
- If reading fails, an alert is triggered.

Environmental data can be logged or displayed on a dashboard for remote monitoring.

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Output:



Applications and other relevant details:

Smart Home:

- Sensor data can be sent to a dashboard or mobile app.
- Supports automation rules like turning on fans, alarms, or notifications when certain conditions are detected.
- Forms the basis of a home security and monitoring system.

Security and Tamper Detection:

- SW-420 Vibration Sensor detects tampering or unauthorized access attempts.
- CAP1203 Touch Sensor can be used to trigger manual alerts or reset systems.
- Provides an early warning system for doors, cabinets, or sensitive devices.
-

Educational / Experimental Use:

- Demonstrates integration of multiple sensors in a microcontroller environment.
- Helps students and hobbyists learn about sensor interfacing, real-time monitoring, and alert systems